

Scheda Dati

020MT1P3TGR

Manipulador, 4 posições, 1 permanente 3 temporárias, H 55



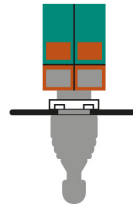
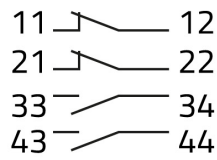
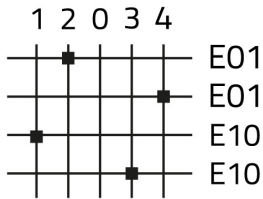
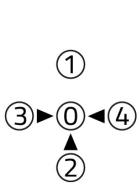
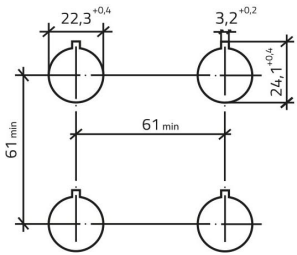
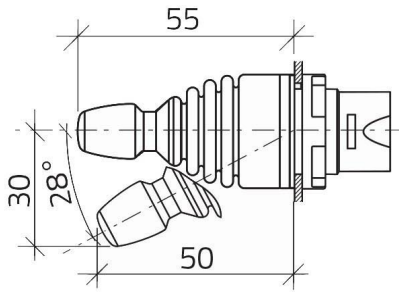
Caratteristiche

| | |
|-------------------------|---|
| Gama | Manipuladores Ø 22 |
| Componente | Manipuladores de 4 posições H 55 mm |
| Código | 020MT1P3TGR |
| Descrição | Manipulador, 4 posições, 1 permanente 3 temporárias, H 55 |
| Cor | Grigio RAL7035 |
| Peso | 38,0 |
| Tariffa doganale | 85365080 |
| GTIN | 8052878067267 |

Dati tecnici

| | |
|---------------------------------------|--|
| Approvals | CE, UL, CSA |
| Compliance with standards | IEC-EN60947-1, IEC-EN60947-5-1, UL508, CSA C22-2 |
| Compliance with standards | UNI CEI EN 45545-2, CEI EN 61373 |
| Operating temperatures | -40° ÷ +70°C |
| Environmental operating values | +25°C-97%RH / +45°C-93%RH (IEC-EN60068-2-30) |
| Protection degree | IP66 - IP69 (IEC-EN60529) |
| Protection against impact | IK03 (IEC-EN62262) |
| Mechanical durability | 1.000.000 Operations |
| Shock resistance | 30g duration=18ms (EN-IEC 60068-2-27) |
| Shock resistance | 50g duration=11ms (EN-IEC 60068-2-27) |
| Vibration resistance | 5g f= 2...500Hz (EN-IEC 60068-2-6) |
| Contact blocks configuration | Max no. 4 blocks (2+2) |
| Material | PA Polyamide |
| Cap or bellow material | Silicon rubber |
| Locking ring material | Zamak zinc alloy |
| Fixing diameter | 22.5mm - Thickness 1÷6mm |
| Tightening torque | 2 ÷ 3Nm (17.7 ÷ 26.6 Lb-in) |
| Warranty period | 18 months |

Disegni tecnici



020G
020E01
020E01
020E10
020E10